IN THE CLAIMS

Please amend the claims as follows:

1-2. (Cancelled).

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3. (Currently Amended) A method of noise filtering a signal, the method comprising the steps of:

estimating a type of noise in the signal; and
enabling one of at least two noise filtering operations,
the enabled noise filtering operation being a most suitable noise
filtering operation for the estimated type of noise,

wherein said enabling step comprises the sub-steps:

enabling a median filtering operation if the estimated

type of noise is long-tailed noise; and

enabling a spatio-temporal rational filtering operation if the estimated type of noise is Gaussian noise or contaminated Gaussian noise,

wherein the sub-step of enabling a spatio-temporal rational filtering operation comprises the further sub-steps:

enabling a first spatio-temporal rational filtering operation if the estimated type of noise is Gaussian noise; and

enabling a second spatio-temporal rational filtering operation if the estimated type of noise is contaminated Gaussian noise,

- and wherein the first spatio-temporal rational filtering operation takes into account at least one temporal direction, and the second spatio-temporal rstional-rational filtering operation takes into account at least one combination of a temporal direction and a spatial direction.
 - 4. (Cancelled).

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5. (Previously Presented) A method of noise filtering a signal, the method comprising the steps of:

estimating a type of noise in the signal; and
enabling one of at least two noise filtering operations,
the enabled noise filtering operation being a most suitable noise
filtering operation for the estimated type of noise,

wherein said enabling step comprises the sub-steps:

enabling a median filtering operation if the estimated

type of noise is long-tailed noise; and

enabling a spatio-temporal rational filtering operation if the estimated type of noise is Gaussian noise or contaminated Gaussian noise,

and wherein:

a kurtosis of the noise is used as a metric for estimating the type of noise;

the median filtering operation is enabled if the kurtosis is above a first threshold; and

the spatio-temporal rational filtering operation is enabled if the kurtosis is below said first threshold.

6. (Currently Amended) The <u>method</u> of noise filtering as claimed in claim 3, wherein:

a kurtosis of the noise is used as a metric for estimating the type of noise;

the median filtering operation is enabled if the kurtosis is above a first threshold;

the first spatio-temporal rational filtering operation is enabled if the kurtosis is below a second threshold, said second threshold being lower than said first threshold; and

the second spatio-temporal rational filtering operation is enabled if the kurtosis is above the second threshold and below the first threshold.

- 7. (Previously Presented) The method of noise filtering as claimed in claim 6, wherein the first threshold is about 15 and the second threshold is about 6.
- 8. (Previously Presented) The method of noise filtering as claimed in claim 3, wherein in said noise estimating step, the

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noise in the signal is estimated by a difference between the signal and a noise-filtered version of the signal.

- 9. (Previously Presented) The method of noise filtering as claimed in claim 8, wherein the noise-filtered version of the signal is obtained by subjecting the signal to a median filtering operation.
- 10-11. (Cancelled).
- 12. (Previously Presented) The method of noise filtering as claimed in claim 5, wherein in said noise estimating step, the noise in the signal is estimated by a difference between the signal and a noise-filtered version of the signal.
- 13. (Previously Presented) The method of noise filtering as claimed in claim 12, wherein the noise-filtered version of the signal is obtained by subjecting the signal to a median filtering operation.
- 14. (Currently Amended) A device for noise filtering a signal, the device comprising:

means for estimating a type of noise in the signal; a median filter for filtering said signal;

a first spatio-temporal rational filter and a second spatio-temporal rational filter for filtering said signal; and means for enabling one of said median filter and said first and second spatio-temporal rational filters, the enabled filter being a most suitable filter for the estimated type of noise.

wherein said enabling means:

enables said median filter if the estimated type of noise is long-tailed noise;

enables said first spatio-temporal rational filter if the estimated type of noise is Gaussian noise; and

enables said second spatio-temporal rational filter if the extimated estimated type of noise is contaminated Gaussian noise,

and wherein the first spatio-temporal rational filter takes into account at least one temporal direction, and the second spatio-temporal rational filter takes into account at least one combination of a temporal direction and a spatial direction.

15. (Previously Presented) A video system comprising:

means for obtaining an image sequence; and

a device as claimed in claim 14 for noise filtering the

image sequence.

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16. (Previously Presented) A device for noise filtering a signal, the device comprising:

means for estimating a type of noise in the signal;

- a median filter for filtering said signal;
- a spatio-temporal rational filter; and

means for enabling one of said median filter and said spatio-temporal rational filter, the enabled filter being a most suitable filter for the estimated type of noise,

wherein said enabling means enables said median filter if

the estimated type of noise is long-tailed noise, and enables said

spatio-temporal rational filter if the estimated type of noise is

Gaussian noise or contaminated Gaussian noise,

wherein said estimating means uses a kurtosis of the noise as a metric for estimating the type of noise,

15 and wherein said enabling means:

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enables said median filter if the kurtosis is above a first threshold; and

enables said spatio-temporal rational filter if the kurtosis is below said first threshold.

17. (Previously Presented) A video system comprising:
means for obtaining an image sequence; and

a device as claimed in claim 16 for noise filtering the image sequence.